

Experimental evaluation of two haptic techniques for 3D interaction: constriction polyhedron / magnetic attraction

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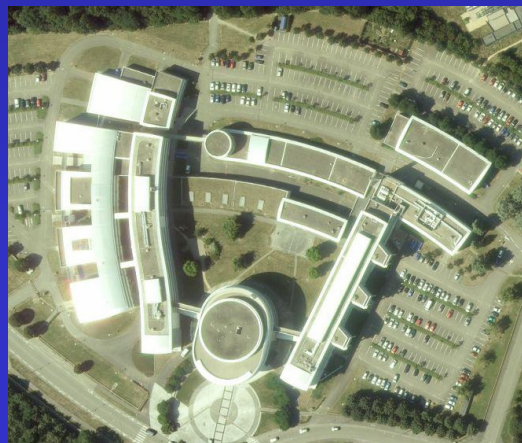
Laboratoire des Sciences de l'Image, de l'Informatique et de la Télédétection (LSiIT)

Strasbourg, France



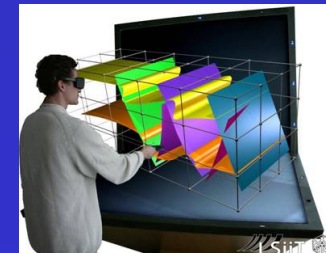
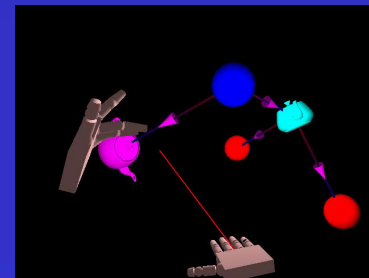
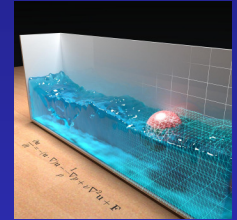
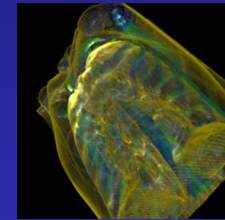
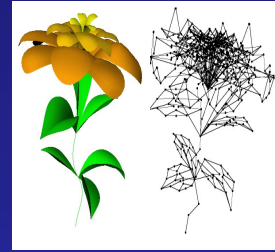
LSiIT Laboratory

- LSiIT: Laboratoire des Sciences de l'Image, de l'Informatique et de la Télédétection (<http://lsiit.u-strasbg.fr>)
 - Joint laboratory: CNRS / Université de Strasbourg
 - Location: Strasbourg, France
 - 150 people
 - 75 faculty members
 - Since 1994



IGG Team: Computational Geometry & Computer Graphics

- 27 members (4 Pr., 9 Assist. Pr., 2 eng.)
- Many research topics around image synthesis & VR
 - Geometric modeling (surface & volume meshing)
 - Deformations
 - Simulation, animation
 - Scientific visualization
 - 3D interaction (virtual reality, haptic interfaces)
 - Proofs and constructions in geometry

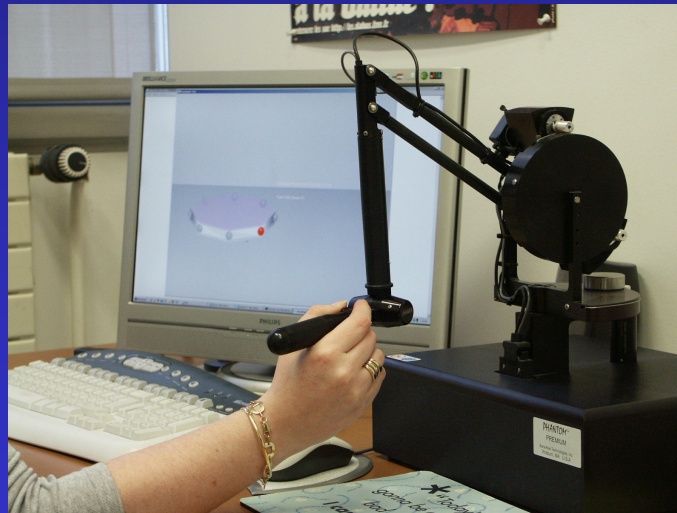


Study: Experimental evaluation of 2 haptic techniques for 3D interaction

- General objective of our work:
 - Enhance navigation and selection of randomly located targets within a 3D space, by using haptics
 - Haptic help in feeling depth
- Objective of this study:
 - First study on a 3D menu (set of targets located in the same plane)
- Preliminary comparative study of 2 haptic techniques:
 - Constriction polyhedron
 - Magnetic attraction
- Comparison with simple 3D interaction with no haptics

Experimental setting

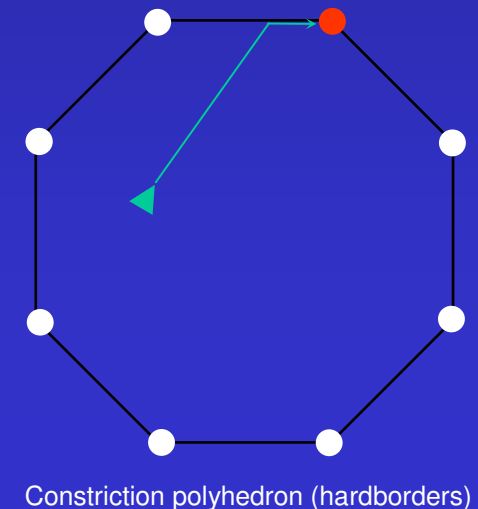
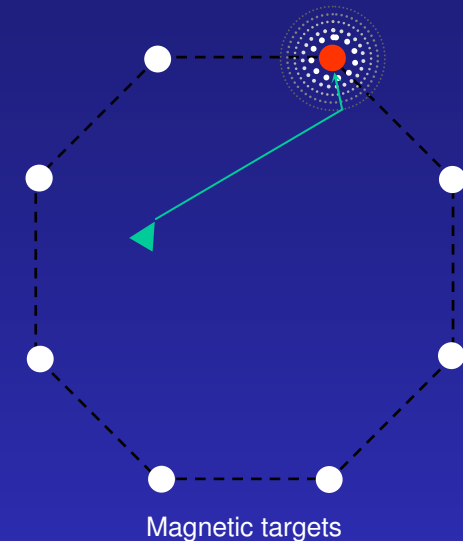
- Device:
 - Phantom Premium 1.5 (Sensable) with 6dof



- Preliminary study → only 6 subjects

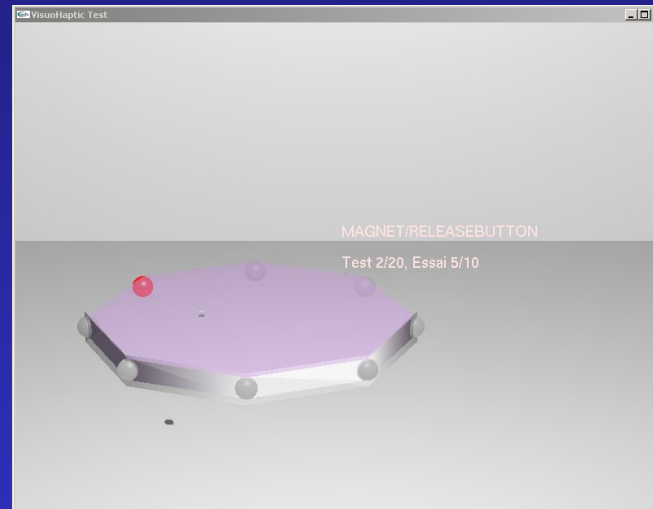
Description of the haptic menu

- Polyhedron shape (≈ "pie shaped")
- Each vertex:
 - small white ball which corresponds to a menu item
- Haptic plane:
 - User has a "tactile basis" where the pointer can lie on
- 2 propositions of haptic guidance to items:
 - Magnetic targets
 - Constriction polyhedron = borders of polyhedron are hard and slippery
- Modifiable parameters:
 - Diameter
 - Number of items (→ shape)
 - Strength of attraction (magnetic targets)
- Oblique 3D menu (not vertical)
 - Possibility to have several layers in the future



Description of task

- Select a randomly located item (red ball) in the menu → vertex



- Three conditions:
 - No haptics : attraction plane, no haptics on the targets
 - Magnet : attraction plane + magnetic attraction on the target
 - Hard borders (constriction polyhedron) : attraction plane + hard borders of the menu
- Measurements (quantitative evaluation) + questionnaire (subjective evaluation)

Task progress

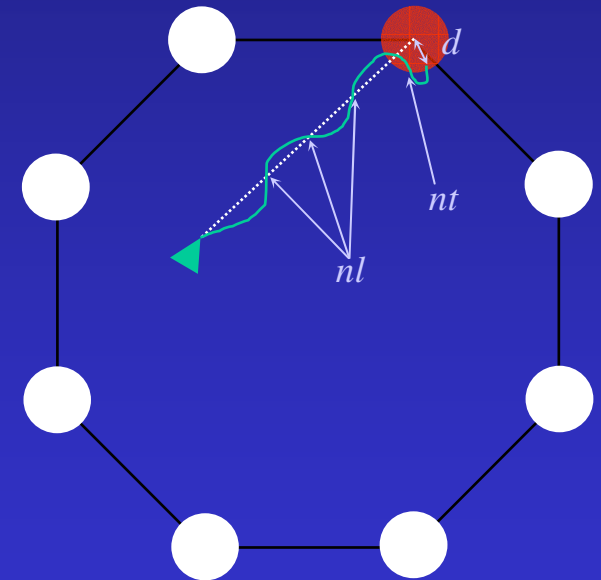
- Task progress:
 - Step 1: menu appears on demand (clic) centered on the pointer
 - Step 2: immediately a randomly selected item highlights (red ball)
 - Step 3: the subject positions the pointer on the item
 - Step 4: the subject validates the selection (clic, again)
 - Step 5: the menu disappears



Measurements

- From step 1 to step 5, we measure:
 - **Task completion time**: Time spent from the apparition of the menu to the validation of the selection
 - **Precision**: Distance between the pointer and the center of the target at the moment of the selection (d)
 - **Axis crossings**: Number of times the pointer has crossed the line connecting the center of the menu and the target (nl)
 - **Target crossings**: Number of times the pointer has crossed the target during the task (nt)

- For each measurement, we calculate probability p :
 - " $p \leq 0.05$ " = "less than 5% chance that the difference is due to coincidence" → significant difference



Experimental results

Task completion times:

- Significant effect of the type of haptics

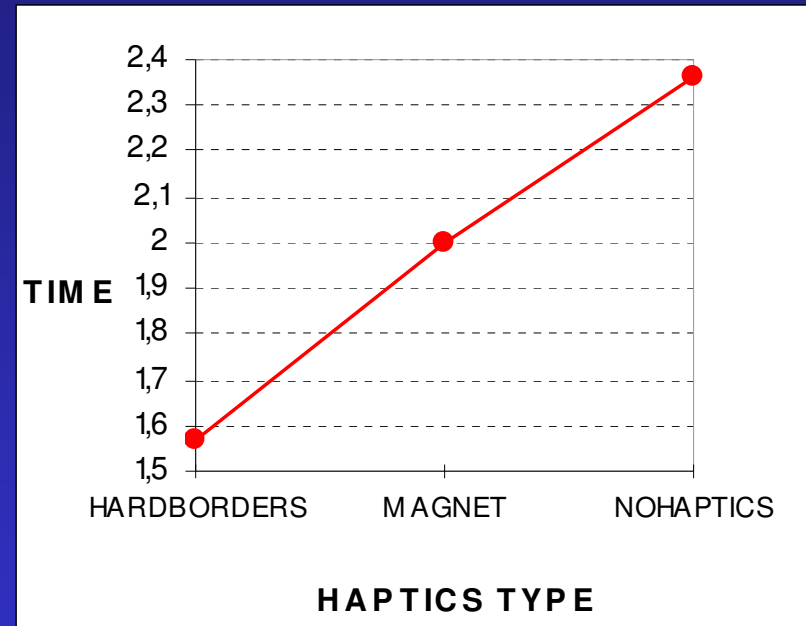
$$F(2,537) = 62.051 \quad p < 0.0001$$

- "Hardborders" technique significantly faster than "magnet"

$$1.559 \text{ s.} \leftrightarrow 2.003 \text{ s.} \quad \text{gain of 22\%} \quad p < 0.0001$$

- "Magnet" significantly faster than "nohaptics"

$$2.003 \text{ s.} \leftrightarrow 2.361 \text{ s.} \quad \text{gain of 15\%} \quad p = 0.001$$



Experimental results

• Precision:

- Significant effect of the type of haptics

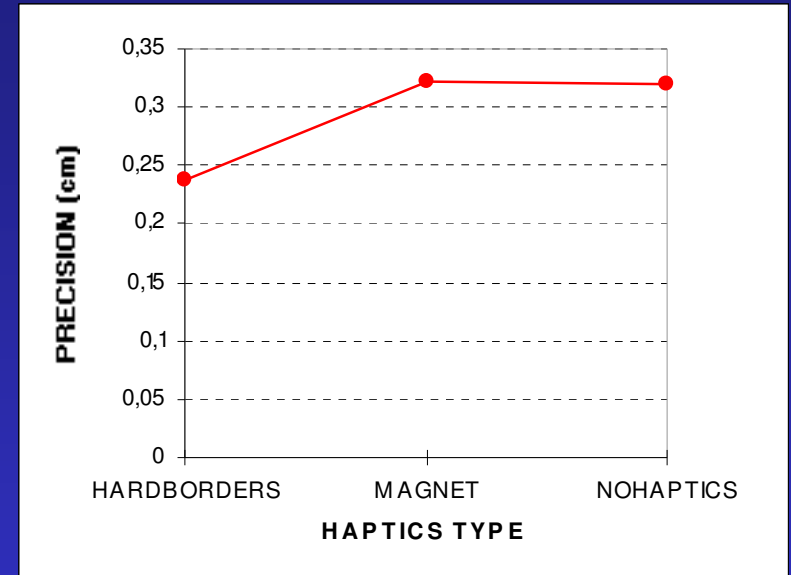
$$F(2,537) = 13.884 \quad p < 0.0001$$

- "*Hardborders*" technique significantly more precise than "*magnet*"

$$0.228 \text{ cm} \leftrightarrow 0.322 \text{ cm} \quad \text{gain of 29\%} \quad p < 0.0001$$

- No statistically significant difference between "*nohaptics*" and "*magnet*"

$$p = 0.956$$



Experimental results

• Target crossing:

- Significant effect of the type of haptics

$$F(2,537) = 6.866 \quad p = 0.001$$

- Target crossing number significantly higher with "*magnet*" than "*hardborders*"

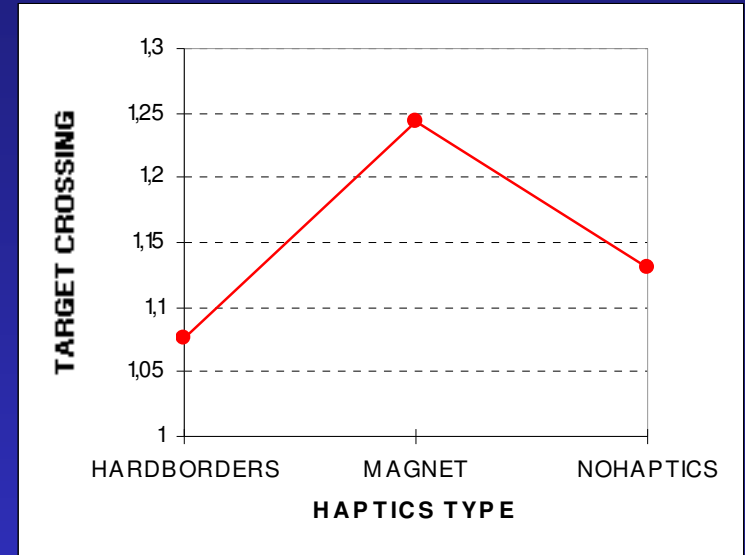
$$1.243 \leftrightarrow 1.075 \quad p < 0.0001$$

- No statistically significant difference between "*nohaptics*" and "*hardborder*"

$$1.13 \leftrightarrow 1.075 \quad p = 0.401$$

- No statistically significant difference between "*nohaptics*" and "*magnet*"

$$1.13 \leftrightarrow 1.243 \quad p = 0.083$$



Experimental results

. Axis crossing:

- Significant effect of the type of haptics

$$F(2,537) = 10.7 \quad p < 0.0001$$

- Axis crossing number significantly higher with "*magnet*" than "*hardborders*"

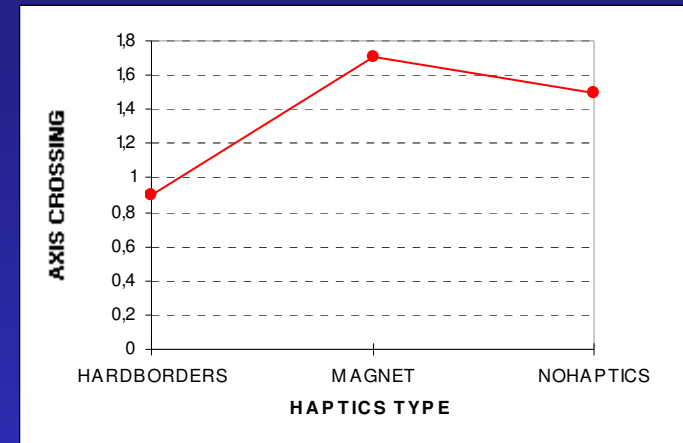
$$0.895 \leftrightarrow 1.709 \quad p < 0.0001$$

- Statistically significant difference between "*nohaptics*" and "*hardborder*"

$$1.5 \leftrightarrow 0.895 \quad p = 0.018$$

- No Statistically significant difference between "*nohaptics*" and "*magnet*"

$$1.5 \leftrightarrow 1.709 \quad p = 0.407$$



Discussion

. Results interpretation:

➤ Magnet:

- 😊 short completion times
- 😞 no gain in precision
- 😞 a tendency to higher number of axis and target crossings
 - **loss of control of the user over the task**
 - (this hypothesis is supported by subjects commentaries)*

➤ Hardborder:

- 😊 shorter completion times
- 😊 gain in precision
- 😊 less axis and target crossings
 - **helps the user to complete the task while maintaining control over the behaviour of the pointer**
 - (this hypothesis is supported by subjects commentaries)*

Questionnaire results

Subjective evaluation: Effort

- Significant effect of the type of haptics

$F(2,537) = 4.617$ $p = 0.013$

- "Nohaptics" vs "hardborder":

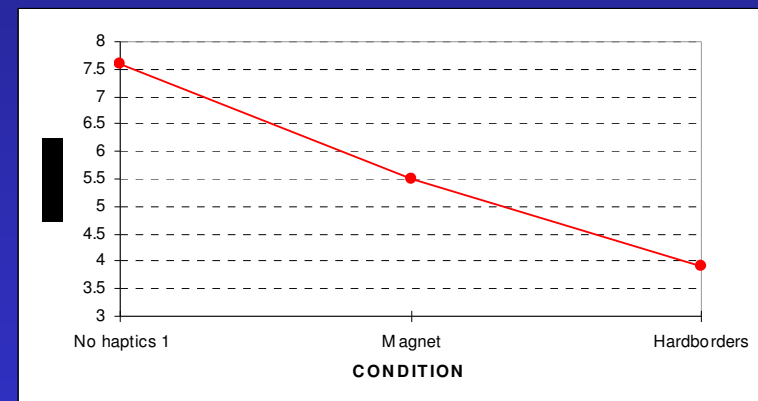
$7.6 \leftrightarrow 3.91$ $p = 0.005$

- "Nohaptics" vs "magnet":

$7.6 \leftrightarrow 5.51$ $p = 0.102$

- "Magnet" vs "hardborder":

$5.51 \leftrightarrow 3.91$ $p = 0.077$



Questionnaire results

. Subjective evaluation: Performance

- Significant effect of the type of haptics

$F(2,537) = 11.986, p < 0.0001$

- "*Nohaptics*" vs "*hardborder*":

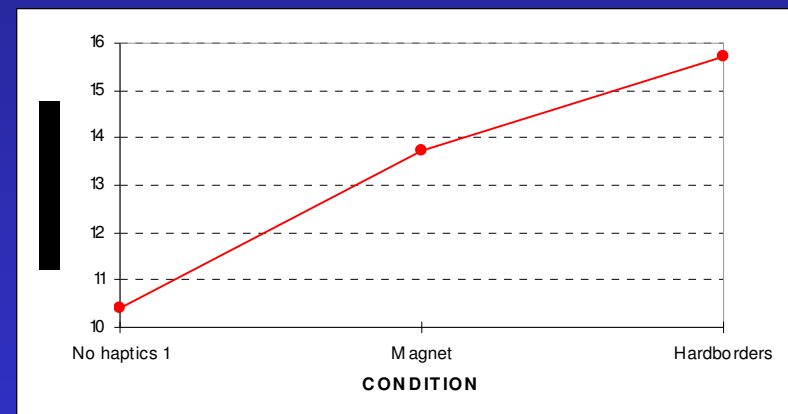
$10.4 \leftrightarrow 15.73, p = 0.005$

- "*Nohaptics*" vs "*magnet*":

$10.4 \leftrightarrow 13.71, p = 0.004$

- "*Magnet*" vs "*hardborder*":

$13.71 \leftrightarrow 15.73, p = 0.012$



Discussion

• Feeling of effort

- Haptics in general help to reduce the subjective feeling of effort
- Statistical tendency to feel less efforts with hardborders compared to magnet

• Feeling of performance

- Haptics in general help to increase the subjective feeling of performance
- Statistically significant difference between all conditions: hardborder leads to increased feeling of performance

Conclusion

- . Preliminary study on a few subjects
 - Haptics are a good way to guide 3D interaction and selection
 - . faster, easier than without haptic guidance
 - "*Hardborders*" technique wins:
 - . better precision and performances
 - . better feelings

- . More complete study will follow with both methods, including:
 - Different values of parameters (diameter, number of items, strength of attraction, ...)
 - Different modes of repulsion from borders (flat, incurved, "star borders"), with or without visualization of the haptic shape
 - Different ways to select (clicking, crossing the target)
 - Different levels of menu (submenus when choosing an item)
 - Different levels in main menu (layers)
 - More subjects

Future works

- Extension to navigation and selection of randomly located targets within a 3D space
 - Main (well known) problems:
 - Great number of objects
 - Occlusions between objects
 - Difficulty to perceive depth
- Haptic guidance to navigate within "convex 3D cells"
 - Haptically enhanced
 - Help overcoming problems

Thanks for your attention

• Questions ?